

# FGS-VC Series Motorized Stand Operation Manual



**NIDEC-SHIMPO CORPORATION**



Read Manual thoroughly prior to operation.

Use instrument only after reading the complete manual.

Follow all safety precautions.

# Safety Precautions

Before Installation, Operation or Maintenance, be sure to read carefully this Operation Manual and use the equipment as directed. Use the equipment after carefully reading all the caution items, safety information, and other discriminations. In this User's Manual, the Safety Awareness Items are divided into three different categories: "Danger", "Warning" and "Caution".

Follow these precautions.



Danger

This symbol indicates if you ignore the contents mentioned and improperly operate, it may lead to serious injury from a potential fire.



Warning

This symbol indicates a potential dangerous situation that could produce a Serious injury if improperly handled.



Caution

This symbol indicates a potential situation that could produce a minor injury or Damage to material if it is improperly handled. However, depending upon the situation, there could be a possibility that it may cause more serious results.

Protection categories are explained and separated by the following symbols.



Proceed with Caution.



Not Allowed-Prohibited.



Mandatory-Must Follow

## ⚠ Warning



|  |  |  |   |
|--|--|--|---|
|  | <p><b>Heavy! Take sufficient care while handling.</b><br/> <b>Ensure stand is placed on a flat, level, stable surface that can support the unit.</b></p> |  | <p><b>Do not operate in areas where explosive gases or vapors may be present.</b></p> |
|  | <p><b>Do not touch the running, inner parts.</b><br/> <b>Keep appendages and loose clothing away from running, moving parts.</b></p>                     |  |   |


## ⚠ Caution

|  |  |  |   |
|--|--|--|---|
|  | <p><b>Fix object surely.</b><br/> <b>There is the possibility of damage.</b></p>   |  | <p><b>Do not install in a high humidity environment or near where water may be present. Electric shock may occur if water is encountered.</b></p> |
|  | <p><b>Hold power plug while removing the power cord.</b> Do not pull or put tension on the cord. Doing so could result in cord damage and electric shock</p> |  | <p><b>Never carry or move the FGS-VC with the AC code.</b><br/>         There is the possibility of electric shock, a fire and injury.</p>        |

|   |   |   |  |
|---|---|---|--|
|  | <p>Confirm that the power supply is the same voltage rating as the displayed voltage rating on the unit</p> |  | <p>Do not plug AC connector with wet hand.<br/>There is the possibility of electric shock.</p> |
|---|---|---|--|

## Attention Safety

|  |  |
|--|--|
|  <b>Warning</b> |  |
|                 | <p>Disconnect from the AC outlet during any maintenance of the stand. Also, unplug when not using for long periods of time.<br/>May cause electric shock, a fire and injury.</p> |

|   |   |
|---|---|
|  <b>Attention before using FGS-VC</b>  |   |
| <p><b>Avoid the following.</b></p> <ul style="list-style-type: none"> <li>Place where water, oil, or medicine may splash</li> <li>Dusty locations</li> <li>Places where condensation occurs</li> <li>Places where explosive gases or ignition sources are present.</li> <li>Place where high vibration may occur</li> <li>Places outside of operating temperature range.<br/>32-104°F (0-40°C)</li> <li>Cleaning with thinner and gasoline, etc.</li> </ul> | <ul style="list-style-type: none"> <li><b>Make sure the cable is not stuck in the stand.</b></li> <li><b>Install the force gauge after turning off the power switch.</b></li> <li><b>Adjust the limit switches when the motor stops.</b></li> </ul> |
| <p><b>When digital force gauge FGV series is installed</b></p> <ul style="list-style-type: none"> <li>Set "ovEr" in the F06 parameter, which is the parameter of Output Type.</li> <li>If "ovEr" is not set, FGS-VC does not stop by the overload of the force gauge.</li> </ul>  |   |

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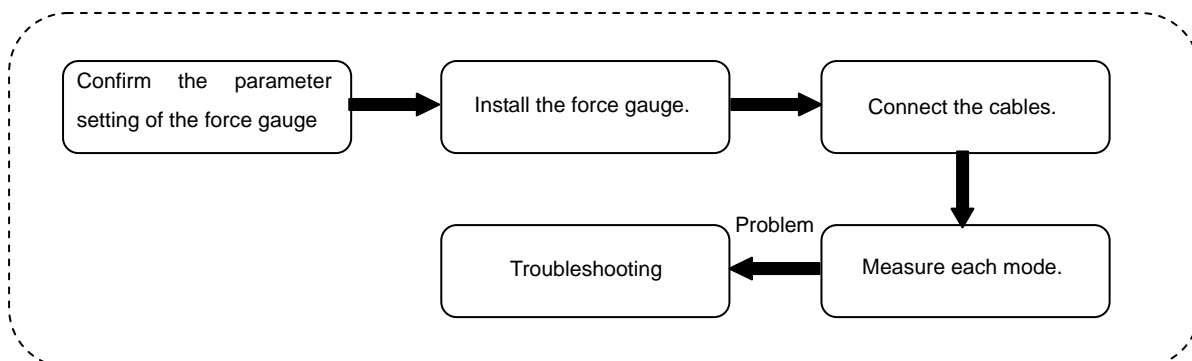
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## 1. Prior to use

### 1.1. Procedure from the Installation of a force gauge to the measurement

FGS-VC can measure various loads using Shimpo's digital force gauges which are FGV series.

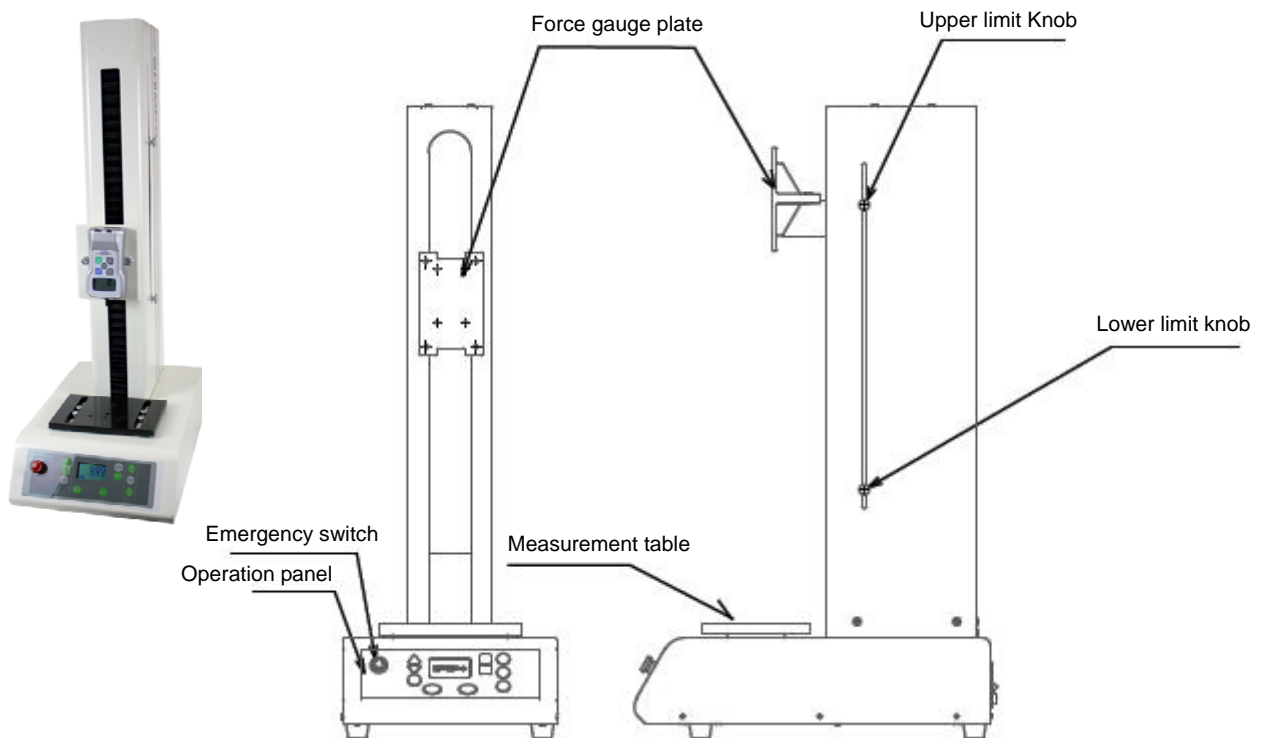
Confirm the following procedures before use.



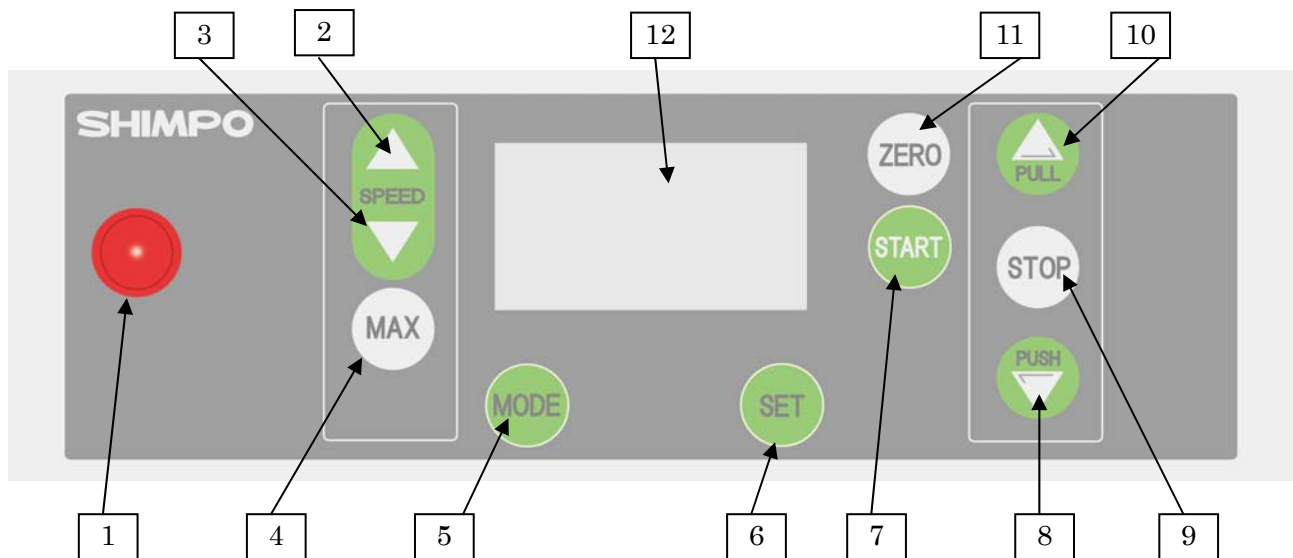
### 1.2. Confirmation of product packing

|                         |   |                       |   |
|-------------------------|---|-----------------------|---|
| FGS-VC                  | 1 | Cable to force gauge  | 1 |
| Cable clip              | 1 | USB cable (2m)        | 1 |
| Hex-head spanner        | 1 | Bolt (M8 x 8mm)       | 4 |
| Socket bolt (M6 x 16mm) | 2 | Set screw (M6 x 20mm) | 1 |
| Washer                  | 2 | Manual                | 1 |

## 2. Names of components



## 3. Names and functions of the operation panel

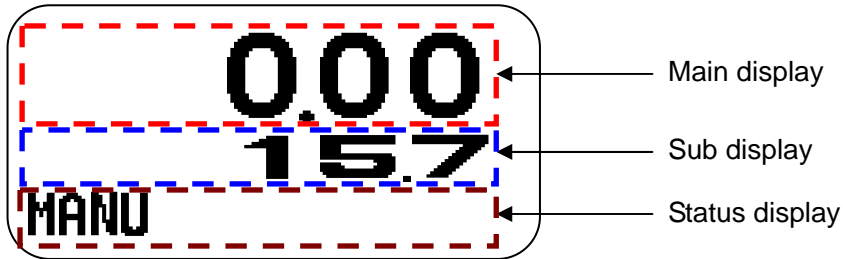


| No | Name             | Description  |
|----|------------------|--|
| 1  | Emergency switch | Emergency stops when pushing. Push the switch when FGS-VC acts abnormally or a potentially dangerous situation is occurring. Release the emergency stop to restart operation.  |
| 2  | Speed key (up)   | Increase or decrease the speed when pushing the up or down arrows of the Speed key. If the up or down arrows are held, the speed adjusts continuously.   |
| 3  | Speed key (Down) |  |
| 4  | MAX key          | Push to override the current speed setting. The speed will instantly go to the maximum capable of the stand. Once released, the speed returns to the previous speed setting. This key only is functional in Manu or Jog modes. |



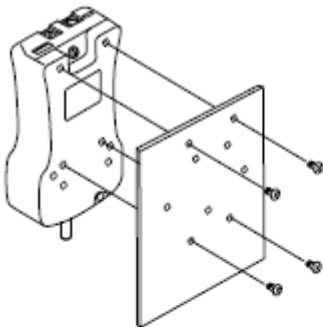
|    |             |  |
|----|-------------|--|
| 5  | MODE key    | Change operation modes or function settings.   |
| 6  | SET key     | The indicated data is set when the key is pushed.  |
| 7  | START key   | Start the program mode operation   |
| 8  | PUSH key    | Move in the PUSH direction.  |
| 9  | STOP key    | Stop operation.  |
| 10 | PULL key    | Move in the PULL direction.  |
| 11 | ZERO key    | Clear distance in Manu and Jog modes.<br>Clear repeat time in Sing, Cont and Prog modes. |
| 12 | LCD display | Displays distance, speed and mode, etc.  |

LCD display



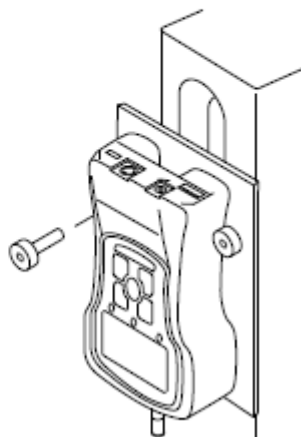
## 4. Setup

### 4.1. Installation of force gauge



The force gauge is set in the mounting plate.

In case of FGS-220VC



The force gauge is fixed to the stand.

Remove the mounting plate using the hex-head spanner accessory.



Set the force gauge in the mounting plate.



Fix the mounting plate with the force gauge to the stand using supplied bolts.



Force gauge that can be connected with FGS-VC is FGV series.  
Force gauges up to 100kgf are compatible with the FGS-220VC.  
Force gauges up to 200kgf are compatible with the FGS-550VC.

## 4.2. Connection of force gauge to the stand

The connection and confirmation between FGS-VC and a force gauge is the following procedure.

**Parameter setting of the force gauge**  
Set the following parameters.  
Measurement polarity: +  
RS232C baud rate: 19,200 bps  
Refer to the manual of the force gauge.



**Connect to FGS-VC**  
Connect the force gauge to FGS-VC by the attached cable.



**Power on**  
Turn on the power of the force gauge.  
Next, turn on FGS-VC with the power switch on the back.



**Confirmation of the connection**  
Display of FGS-VC as follows:  
1. Indicates "FGS-220VC".  
2. Indicates "MANU"(Manual Mode)  
If the connection is wrong,  
2. Indicate "NO FORCE GAUGE" in 3 seconds, then indicate "MANU".

**FGS-220VC**  
**SHIMPO**

**FGS-550VC**  
**SHIMPO**

**0.00**  
**15.7**  
**MANU**

**FGS-220VC**  
**NO FORCE GAUGE**

If the connection is wrong, check:

Are the parameter settings of the force gauge correct?

Is the sequence of power on correct?

Is the cable correct?

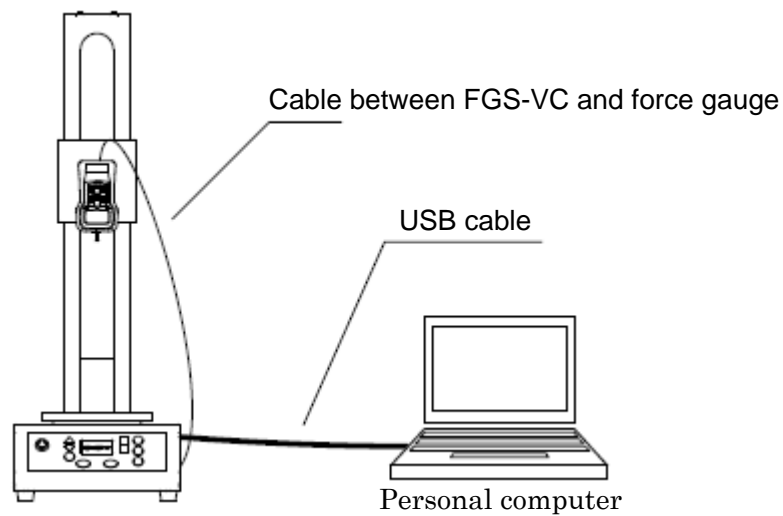
If no problem, please contact our technical support.

### 4.3. Connection of PC to the stand

FGS-VC can connect to PC for taking force and displacement.

The software is able to be downloaded from Shimpo's website free of charge.

Refer to the software manual.



## 5. Operation

### 5.1. Basic operation flow

The procedure of basic operation is described as follows.



**Keep hands, hair and jewelry away from stand when drive assembly is in motion.**  
May cause damage or injury.

#### Force gauge power

Turn on the power of the force gauge.

#### FGS-VC power

Turn on the power of the stand.

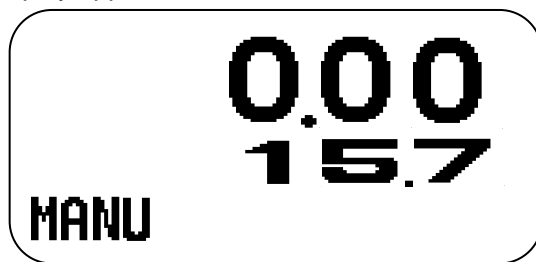
Separate hands from the force gauge and FGS-VC movable parts.

Turn on FGS-VC.

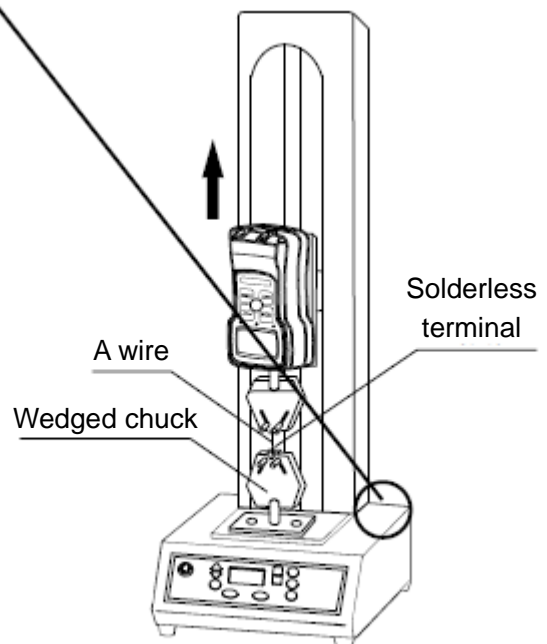
FGS-220VC  
SHIMPO

FGS-550VC  
SHIMPO

Display appears as below:



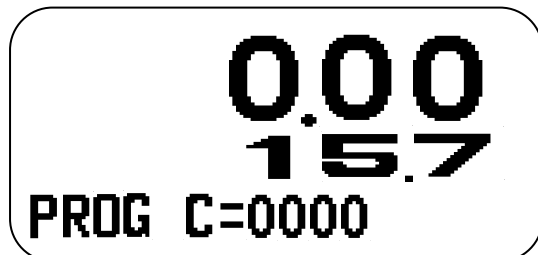
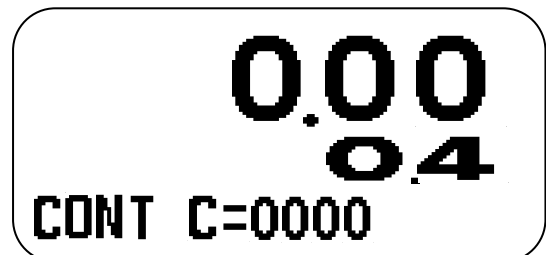
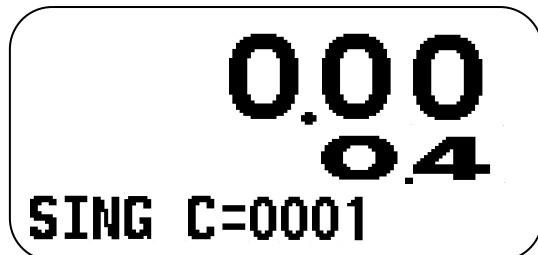
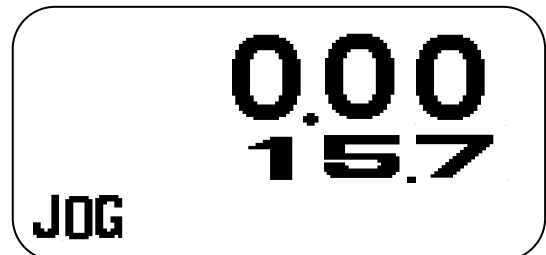
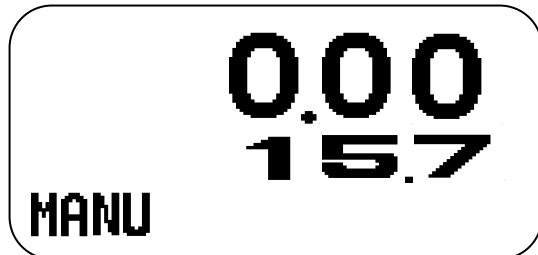
Example. Tension test of a wire



## Select measurement mode

Select Manual, Jog, Single, Continuous and Program mode according to the measurement purpose and the usage.

Mode can be changed by the Mode switch.



## Start to measure.

Start each mode by pressing PUSH, PULL or START switch.

Refer to each mode section.

FGS-VC is able to test as follows:

- Compression test
- Tension test
- Welding test
- Peel test
- Suction test
- Repulsion test
- Cork test
- Open test
- Etc.

## 5.2. Operation mode

The operation mode consists of manual and program.

The mode is selected by the measurement purpose and the usage.

**You wish to test by PUSH or PULL key.**

e.g.,

- You want to move to the position of PULL limit by pressing PULL switch.
- You want to move only while you press the PUSH key.
- You want to move the round trip operation many times between limits of PUSH and PULL.

etc.

Select **manual operation modes** :

**You wish to move complex operations.**

e.g.,

- You want to measure by specifying the positions.
- The position of the object to be measured cannot be specified.
- You want to combine a different direction (PUSH/PULL) of operation with a test.

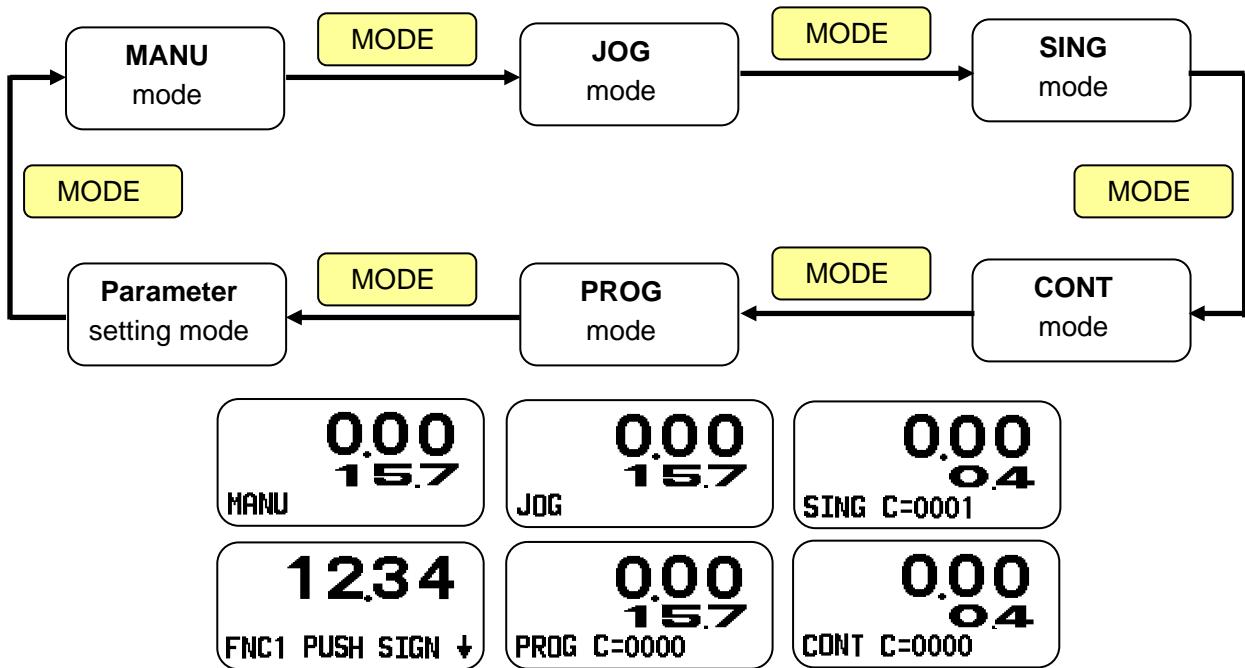
etc.

Select **Program operation mode.**

### How to select the mode?

Pressing MODE switch in the Operation panel, the mode changes one by one as follows.

A present operational mode is displayed under the left of LCD.



### 5.3. Manual operation mode

The manual operation modes are MANU, JOG, SING and CONT.

The mode is selected by the measurement purpose and the usage.

When pressing the PUSH (PULL) key, FGS-VC goes to PUSH (PULL) limit switch position.

FGS-VC stops if reaching the limit position.

#### MANU mode

This mode of operation is identical to MANU, except that the movement in any direction will only occur while either the PUSH or PULL key is depressed.

#### JOG mode

Pressing PUSH or PULL keys, FGS-VC moves for one complete cycle between mechanical distance limit stops.

#### SING mode

Pressing PUSH or PULL keys, FGS-VC moves repeatedly up and down between the mechanical distance limit stops.

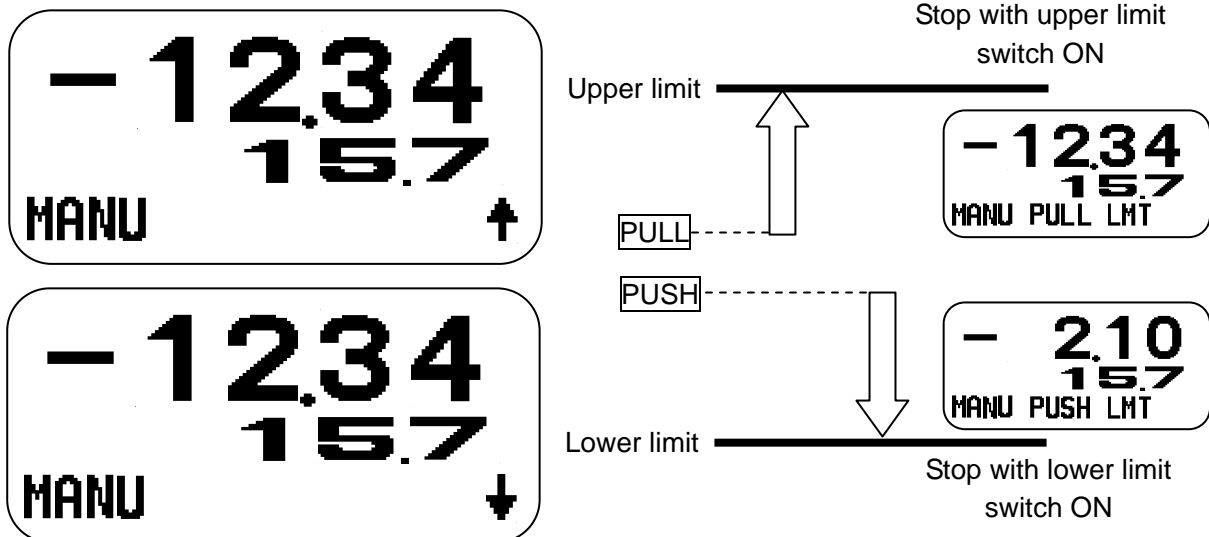
#### CONT mode

#### 5.3.1. MANU mode

This mode of operation is ideal for manually recording force measurements. The test stand will only operate between the limits that are set by the test stand user. These are manually adjusted distance limits.

##### Contents

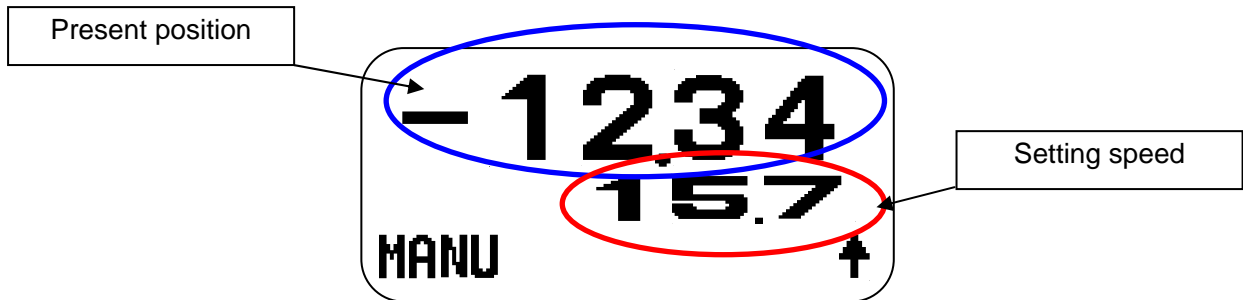
The test stand will move in the downward or upward direction when the respective **PUSH** or **PULL** button is selected. The stand will continue to move in the selected direction until one of the following occurs: **STOP** button is pushed, one of the limit stop switches is tripped or the emergency reset button is pushed.



### Speed

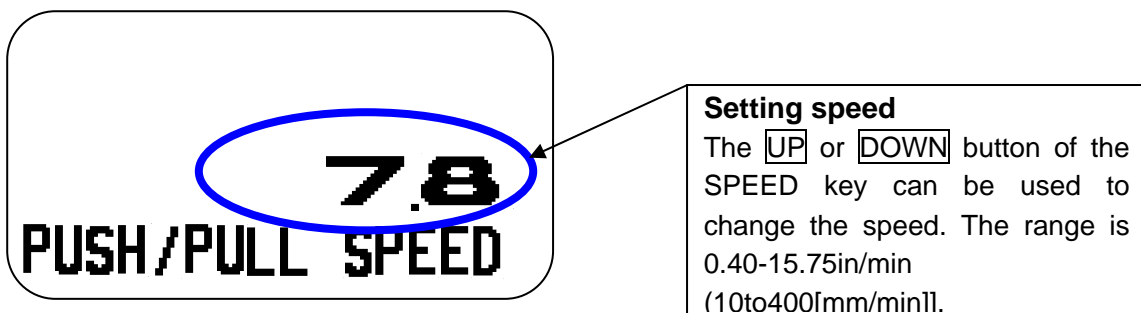
Speed can be changed by **UP** or **DOWN** button of the SPEED.  
The speed setting of MANU and JOG mode is common.  
Also the speed is able to be changed while moving.

### Display



### Parameter

The speed of MANU and JOG modes is adjustable. Press the **SET** button to enable adjustment via the **UP** or **DOWN** buttons of the SPEED key. Then press the **SET** button to save the new value. If you want to cancel the setting press the **ZERO** button.



### 5.3.2. JOG mode

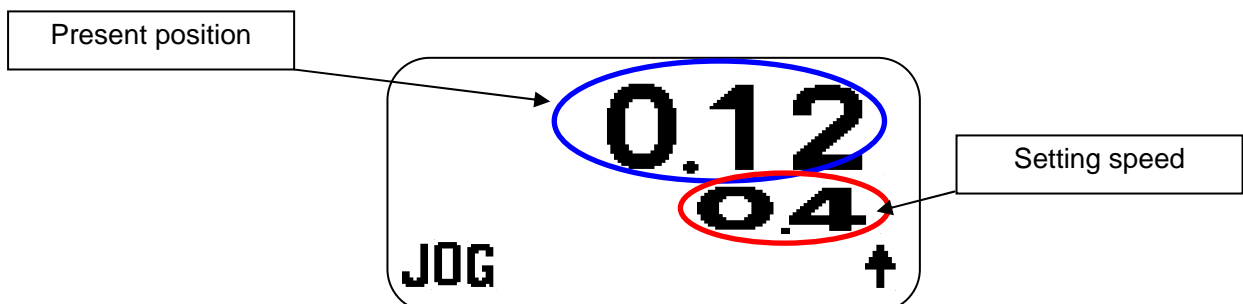
#### Contents

This mode of operation is identical to MANU mode, except that the movement in any direction will only occur while either the **PUSH** or **PULL** button is depressed.

#### Speed

Speed can be changed by **UP** or **DOWN** button of the SPEED key.  
The speed setting of MANU and JOG mode is common.  
Also the speed is able to be changed while moving.

#### Display



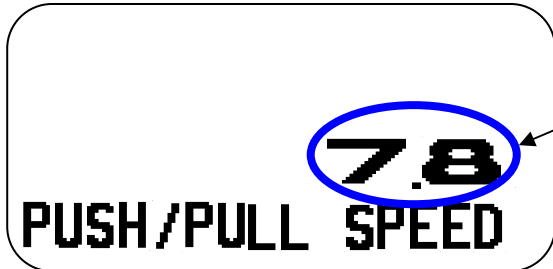
### Parameter

The parameter, which is the speed of MANU and JOG mode, is available.

Pressing **SET** button, and the speed can be changed by **UP** or **DOWN** key of the SPEED.

Then press **SET** button for saving.

If you want to cancel the setting, press **ZERO** button.



### Setting speed

The **UP** or **DOWN** button of the SPEED key can be used to change the speed. The range is 0.40-15.75 in/min (10 to 400[mm/min])



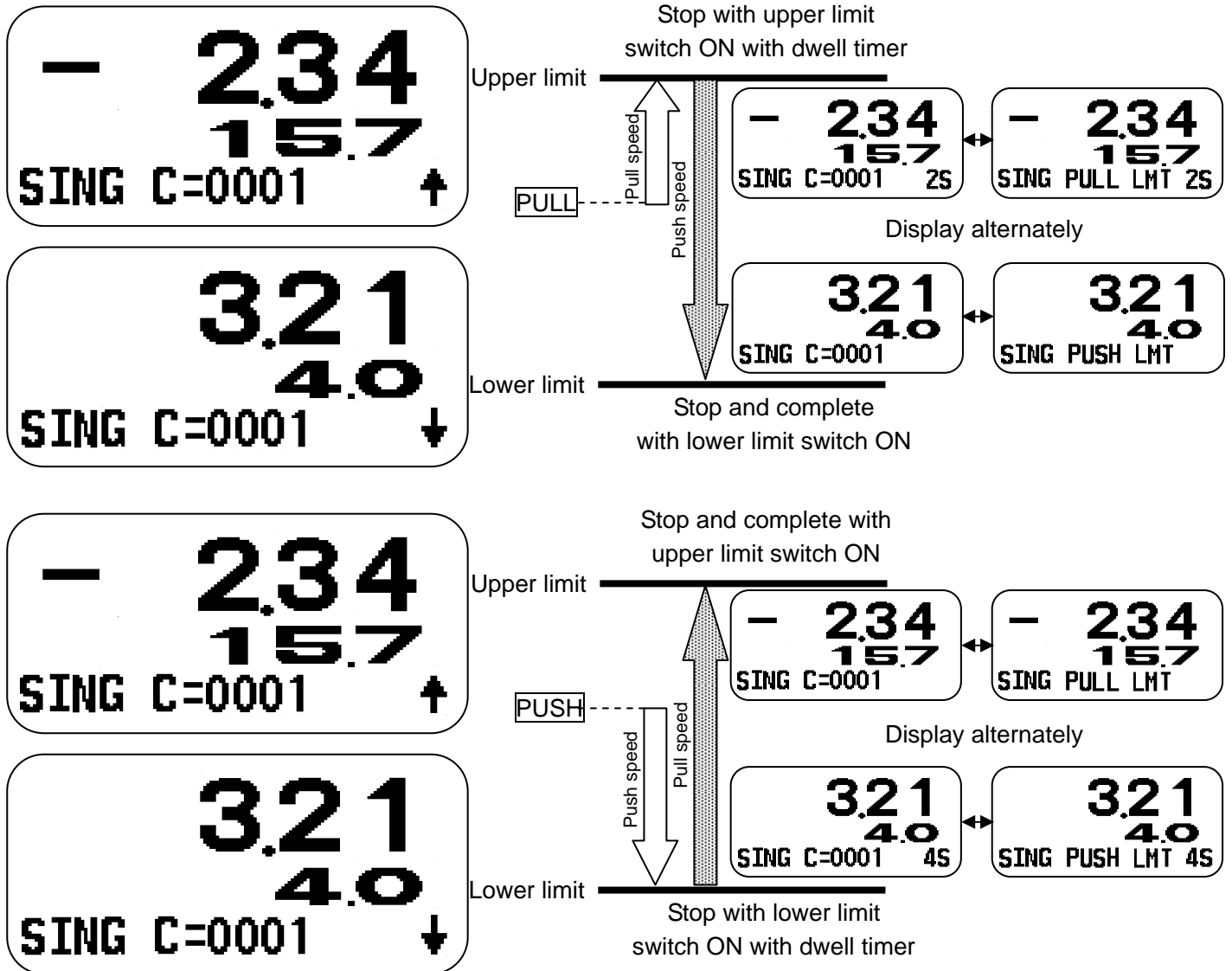
### 5.3.3. SING mode

This mode of operation is ideal for completing one cycle between mechanical, manually adjusted distance limit stops. The test stand will only operate between the limits that are set by the test stand user.

#### Contents

The test stand will move downward or upward when the respective **PUSH** or **PULL** button is selected.

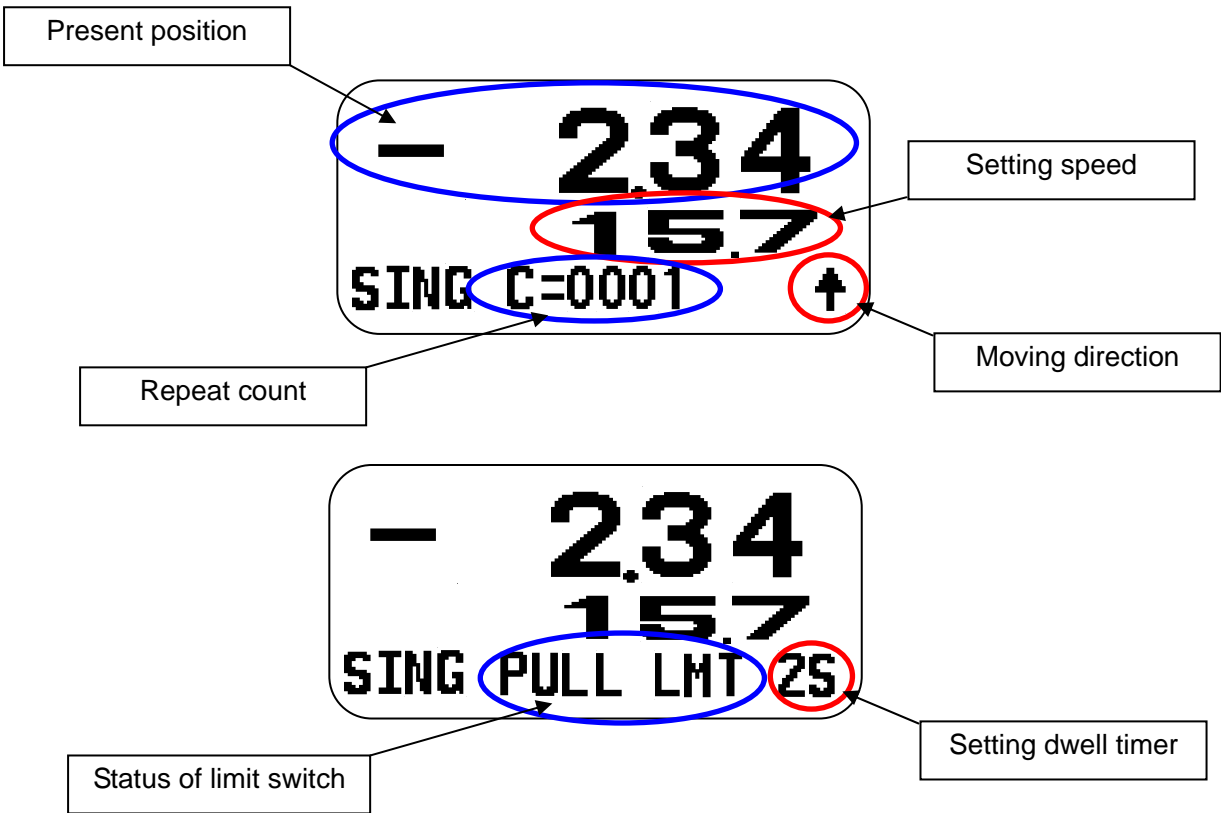
The stand will continue to move until one of the following events occurs: the **STOP** button is pushed, one of the limit switches is tripped or the emergency reset button is pushed.



**Speed**

Speed can be changed by **UP** or **DOWN** button of the SPEED key.  
The speed setting of SING and CONT mode is common.  
Also the speed is able to be changed while moving.

**Display**



**Repeat count**

Incremental count at pressing **PUSH** or **PULL** button.  
The count is cleared with the **ZERO** button. When the mode is changed, the count will also be reset to zero.

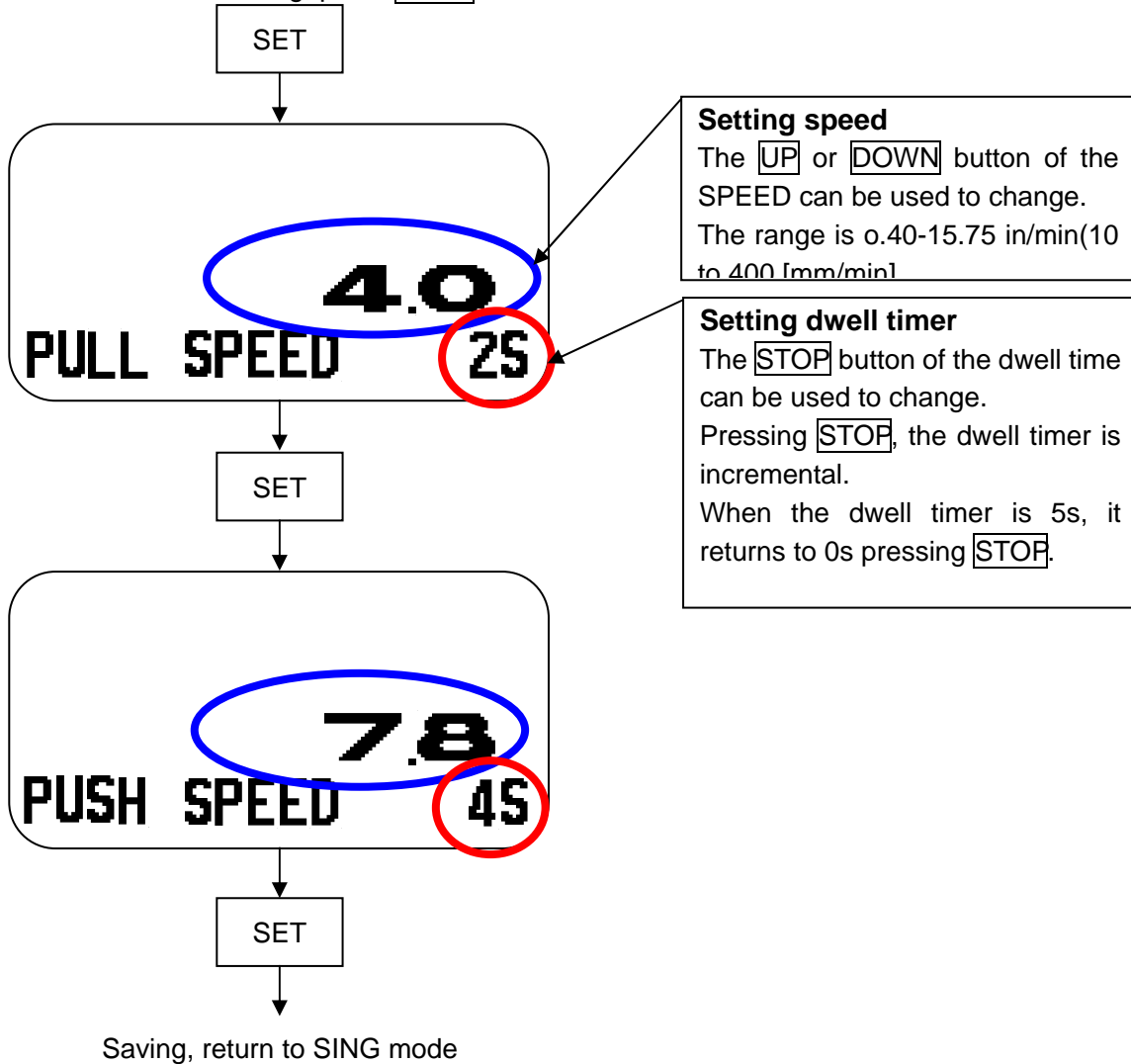
**Parameter**

The parameter, which is the dwell timer and the speed of pull and push, is available.

Pressing **SET** button, the speed can be changed by **UP** or **DOWN** button of the SPEED key. The dwell timer can be changed by **STOP**.

Finally press **SET** button for saving.

If you want to cancel the setting, press **ZERO** button.

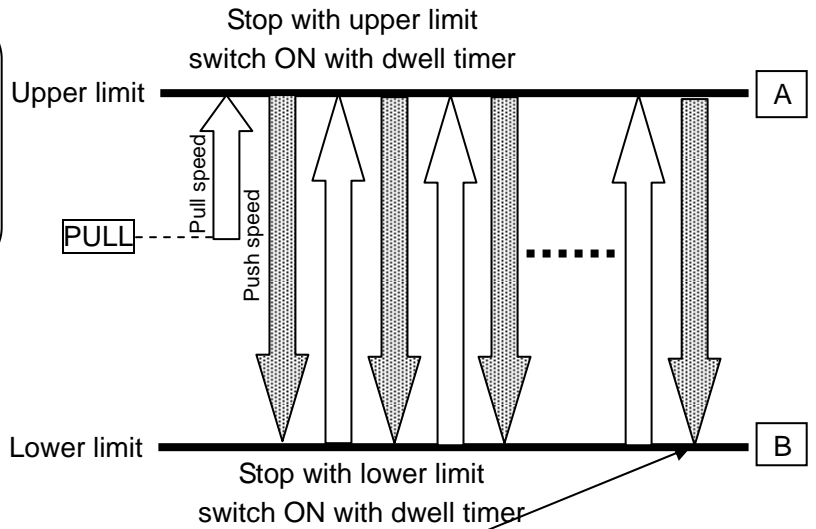
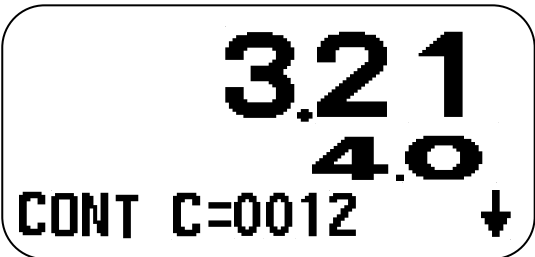


**5.3.4. CONT mode**

This mode of operation is ideal if the user wants the test stand to repeatedly cycle up and down continuously or for a user-programmed number of times. The stand will start in either direction depending on whether **PUSH** or **PULL** button is selected.

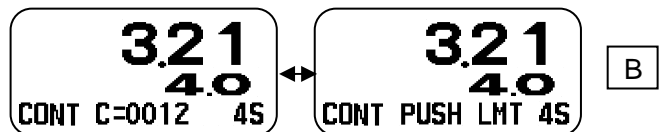
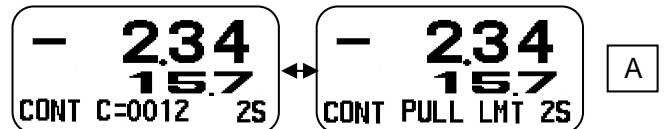
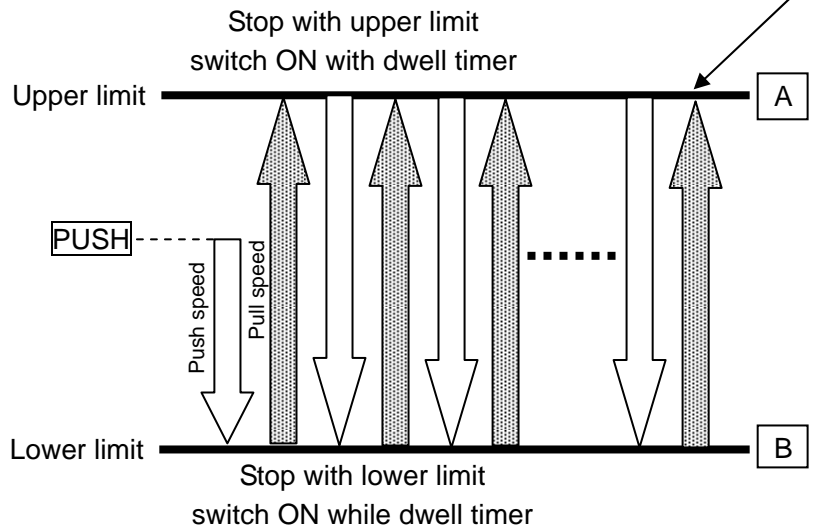
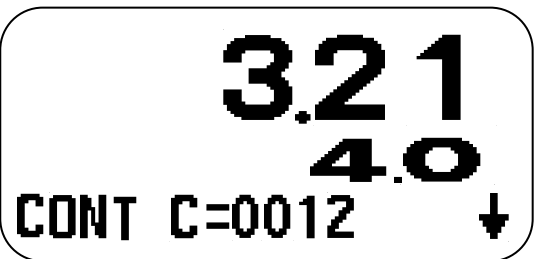
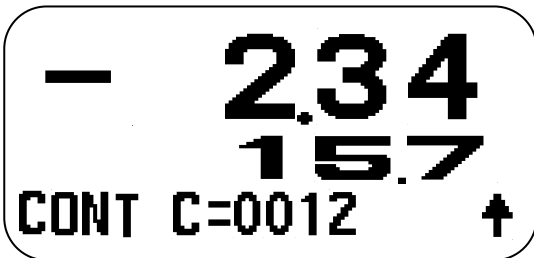
**Contents**

The test stand will start to move downward or upward when the respective **PUSH** or **PULL** button is selected. The stand will continue to move until one of the following events occurs: the **STOP** button is pushed, the emergency reset button is pushed.



Complete with lower limit switch ON when the repeat count is reached.

Complete with upper limit switch ON when the repeat count is reached.



Display alternately

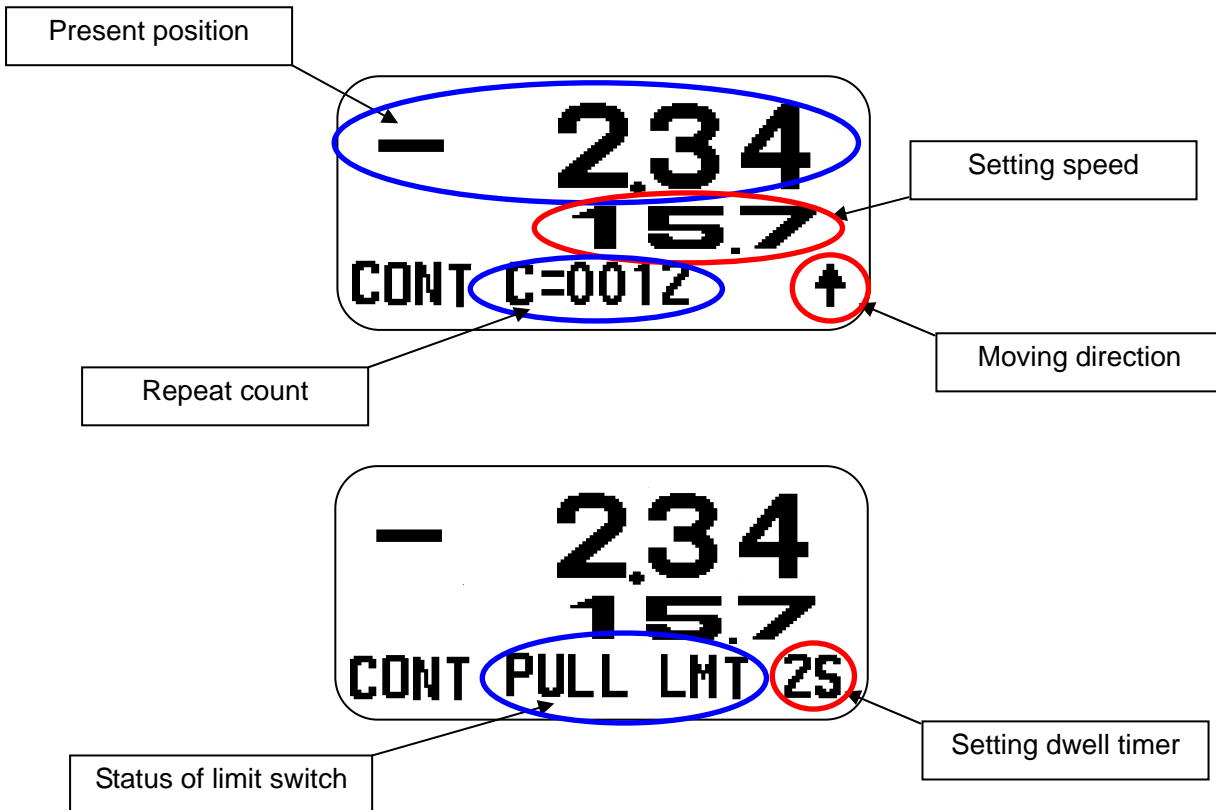
### Speed

Speed can be changed by **UP** or **DOWN** button of the SPEED.

The speed setting of SING and CONT mode is common.

Also the speed is able to be changed while moving.

### Display



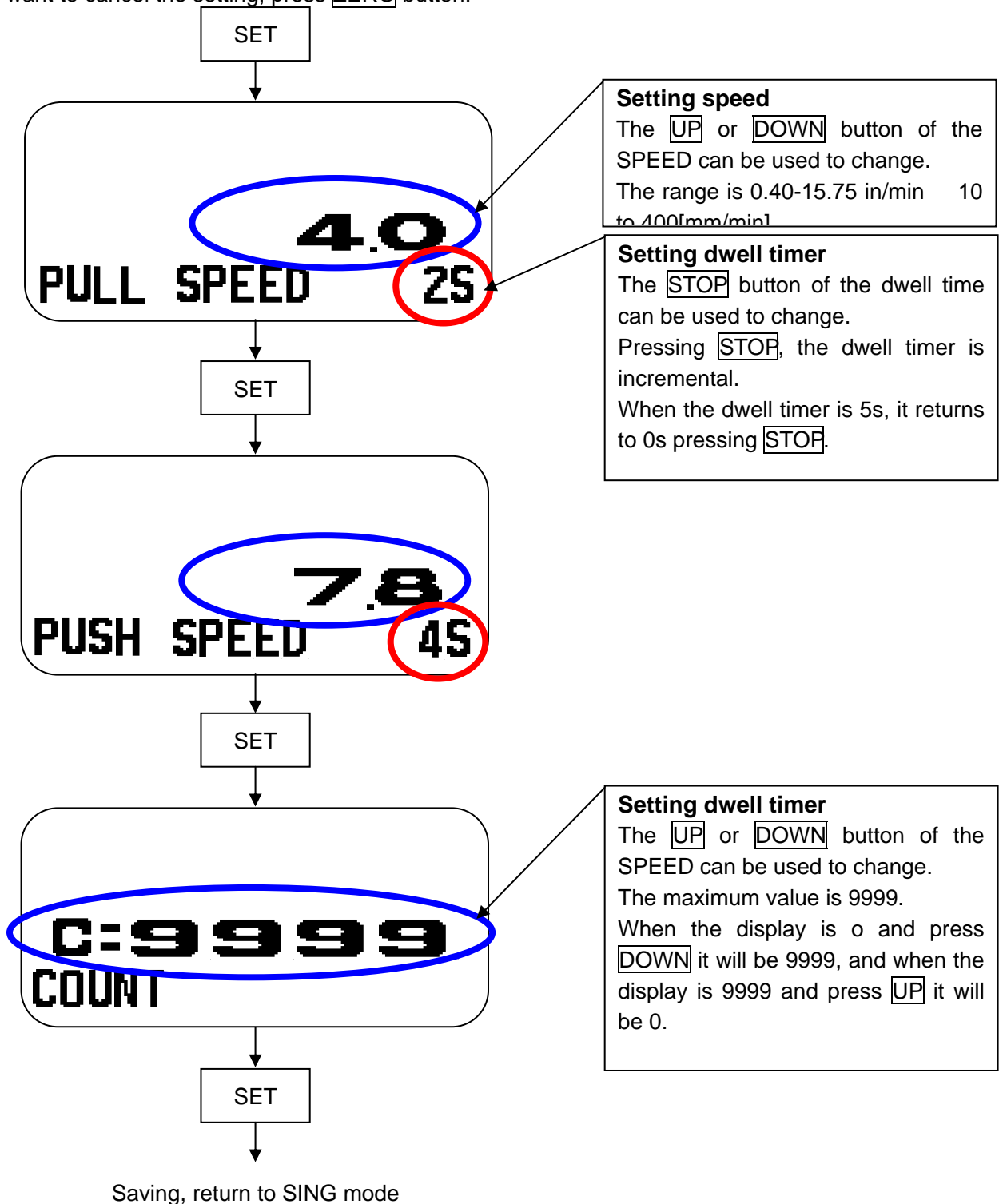
### Repeat count

Incremental count at pressing **PUSH** or **PULL** button.

The count is cleared with the **ZERO** button. When the mode is changed, the count will also be reset to zero.

**Parameter**

The parameter, which is the repeat times and the dwell timer and the speed of pull and push, is available. Pressing **SET** button, the speed and the repeat times can be changed by **UP** or **DOWN** button of the SPEED key, the dwell timer can be changed by **STOP**. Finally press **SET** button for saving. If you want to cancel the setting, press **ZERO** button.



## 5.4. Program operation mode

### 5.4.1. PROG mode

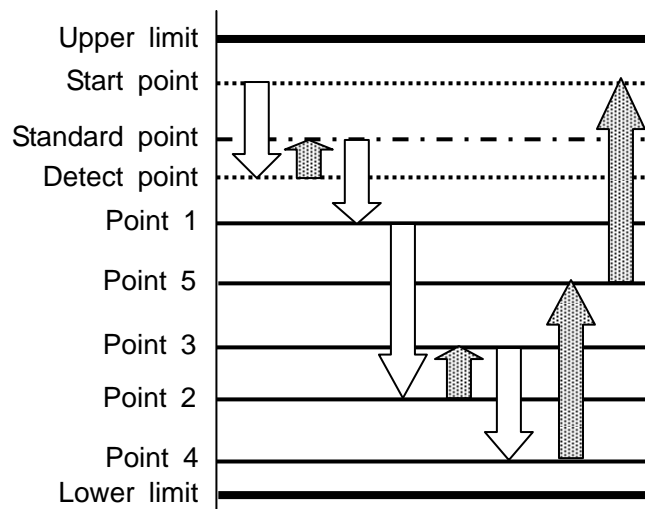
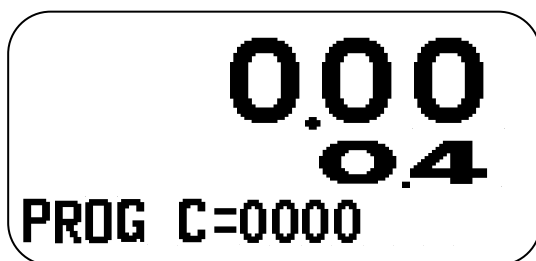
This mode of operation is ideal if user wants to operate the test stand with complex programmed movements. Even if the user does not know the length of the object, the accurate measurement is possible because the function to detect the object to be measured is provided.

#### Contents

The programmed data consists of a condition setting, starting point, a method of detection of the object, five measurement points and a method of return.

The test stand will start to move when **START** button is pressed.

The stand will continue to move until one of the following events occurs: the **STOP** button is pushed, one of the mechanical limit switches is tripped, the emergency reset button is pushed or the overload of the force gauge is detected. If the force limit of the condition setting is detected, the present operation is interrupted and it will jump to next point operation.

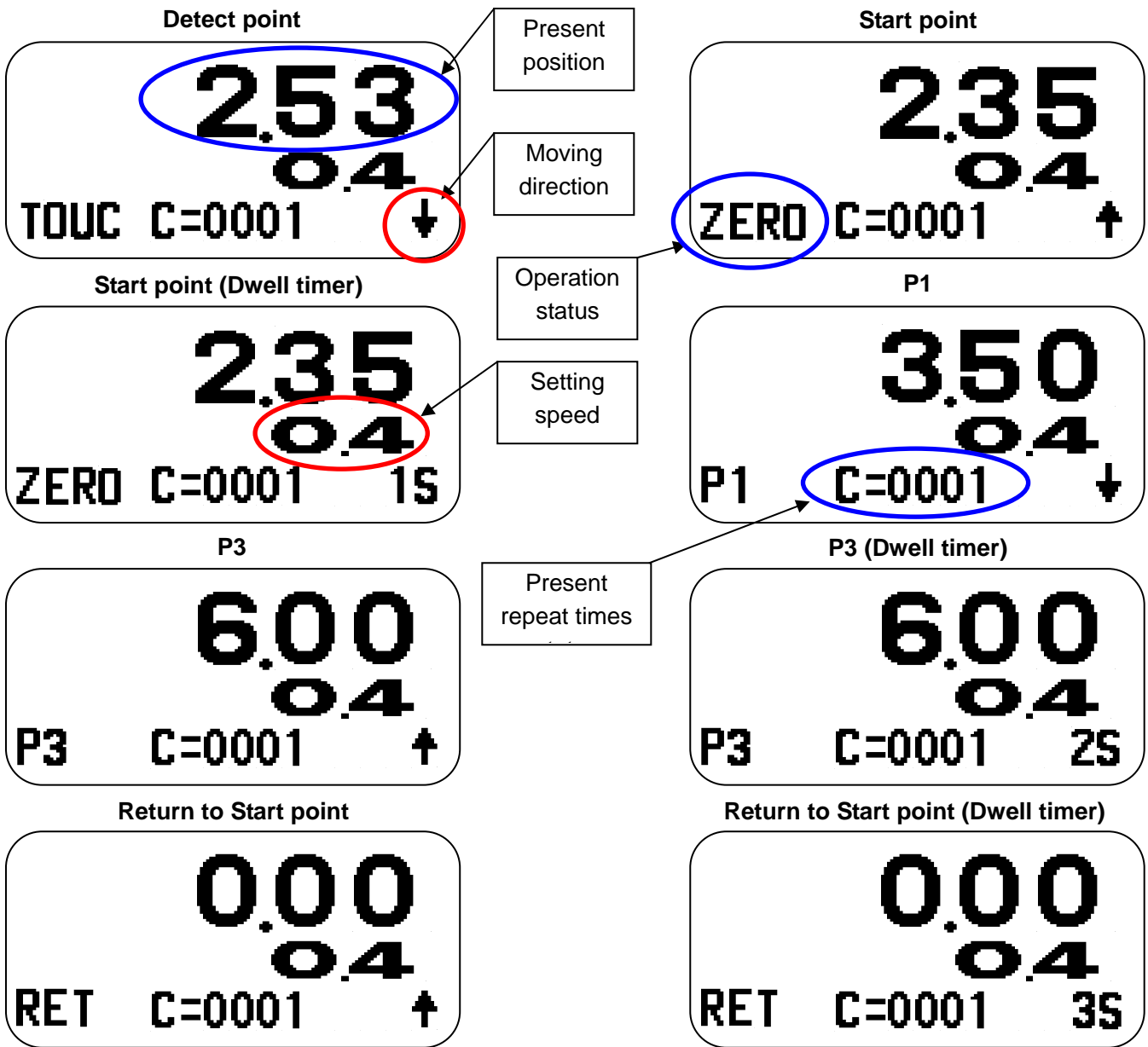


Example

|                |  |
|----------------|--|
| Start point    | Program start point and return point             |
| Detect point   | Object detected point according to the condition |
| Standard point | Standard point for measurement                   |
| Point 1 to 5   | Programmed point                                 |

Display

The example of the display under operation is shown below.





**Parameter**

The parameters are available while stopping.

Pressing **SET** button, the parameter setting starts.

The contents of the parameters setting is shown in the below flowchart.

Finally press **SET** button for saving.

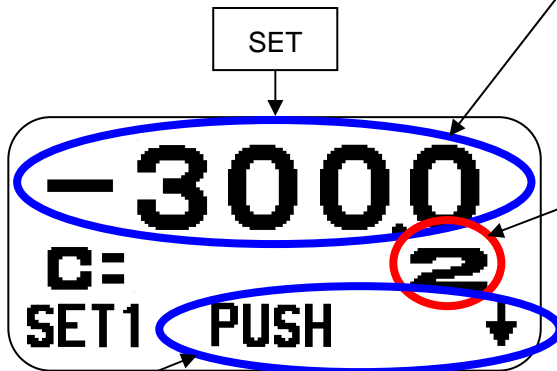
If you want to cancel the setting, press **ZERO** button.

**Condition setting**

**Moving direction**

The parameter is the direction of movement from "Start point" to "Detect point".

The **STOP** button can be changed to Push or Pull alternately.



**Force limit**

The **PUSH** or **PULL** button can be used to change.

The sign of force limit is changed by **MAX** button alternately.

**Repeat times**

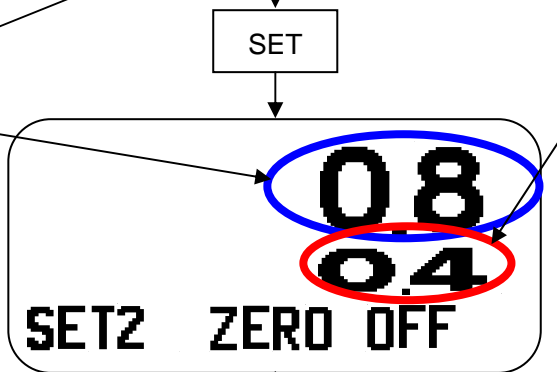
The **UP** or **DOWN** button of the SPEED can be used to change.

The maximum value is 9999.

When the display is 0 and press **DOWN** it will be 9999, and when the display is 9999 and press **UP** it will be 0.

**Detect object**

The force for detecting object can be set by **PUSH** or **PULL** button.



**Speed**

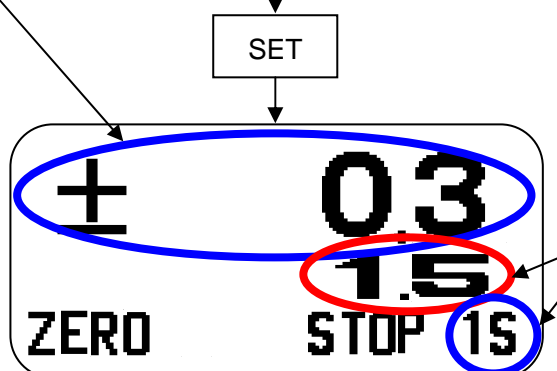
The parameter is the speed setting for moving from "Start point" to "Detect point".

The **UP** or **DOWN** button of the SPEED can be used to change.

**Zero force**

After detecting the object, the stand moves to opposite direction until sensing the force less than the setting force data.

The **PUSH** or **PULL** button can be used to change.



**Speed**

The parameter is the speed setting for moving from "Detect point" to "Standard point".

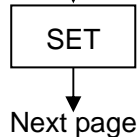
The **UP** or **DOWN** button of the SPEED can be changed.

**Dwell timer**

The parameter is the dwell timer at "Standard point".

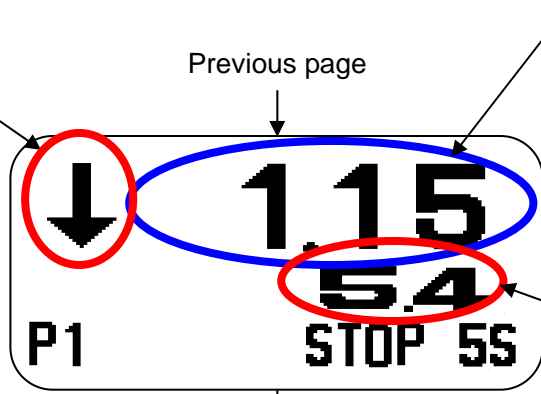
Pressing **STOP**, the dwell timer is incremental.

When the dwell timer is 5s, it returns to 0s pressing **STOP**.



**Point 1 to 5**

**Movement direction at P1**  
 The parameter is the direction of movement from "Standard point" to "Point 1".  
 The **MAX** button can be changed to Push or Pull



**Movement Distance at P1**  
 The parameter is the distance from "Standard point" to "P1".  
 Also the data should be set as relative coordination.  
 The **PUSH** or **PULL** button can be used to change.

**Speed at P1**  
 This parameter is the speed setting for moving from "Start point" to "Detect point".  
 The **UP** or **DOWN** button of the **SPEED** can be used to change.

SET

**Setting P2 to P4**

SET



**Dwell timer at P5**  
 This parameter is the dwell timer.  
 Pressing **STOP**, the dwell timer is incremental.  
 When the dwell timer is 5s, it returns to 0s pressing **STOP**.

**Speed at RET**  
 This parameter is the speed setting for moving from "Point 5" to "Start point".  
 The **UP** or **DOWN** button of the **SPEED** can be used to change.

SET

**Return to "Start point"**



**Dwell timer at RET**  
 This parameter is the dwell timer.  
 Pressing **STOP**, the dwell timer is incremental.  
 When the dwell timer is 5s, it returns to 0s pressing **STOP**.

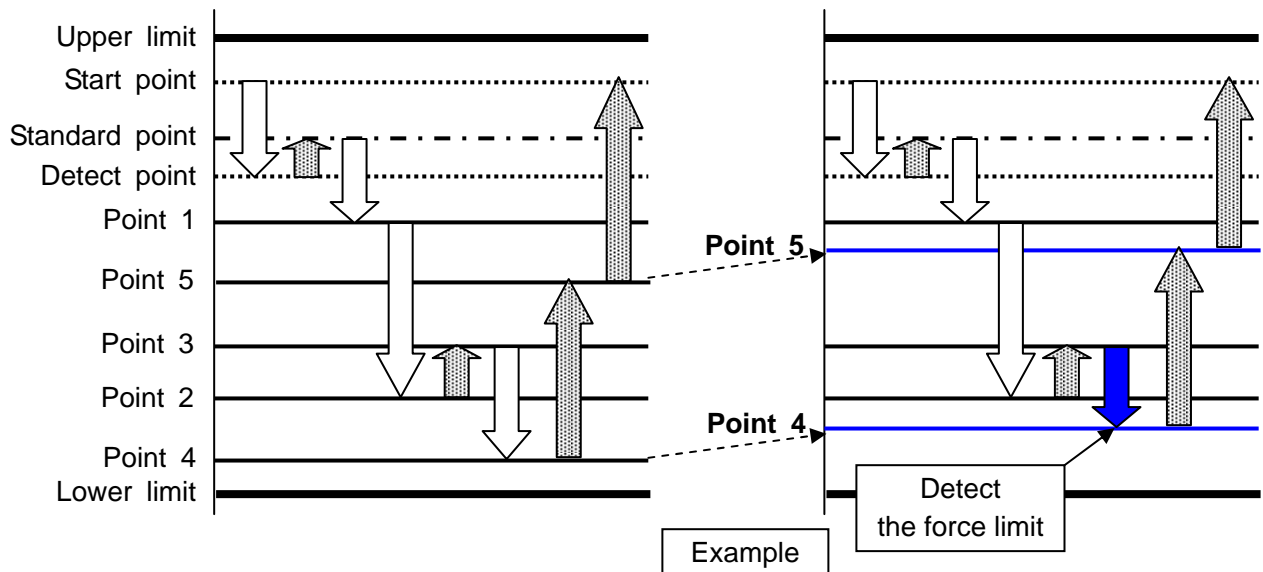
SET

Saving, return to PROG mode

**Force limit**

The stand controls to give the force less than the "Force limit".

If the force limit is detected, the stand will stop immediately. Then the stand executes the next step.



**Detect object**

The parameter is the threshold force level for detecting the object.

When the setting force of "Detect object" parameter is detected, the stand will stop immediately. Next the stand moves to opposite direction until detecting "Zero force".

The recommended "Detect object" that the user should program into the stand is more than 0.2% of the full scale of the mounted force gauge, i.e., if the programmer is using a 200lb force gauge, the programmed "Detect object" should be 0.4lb (200lb x 0.2%).

**5.5. Parameter setting mode**

The relations function is set to the entire stand.

**Contents**

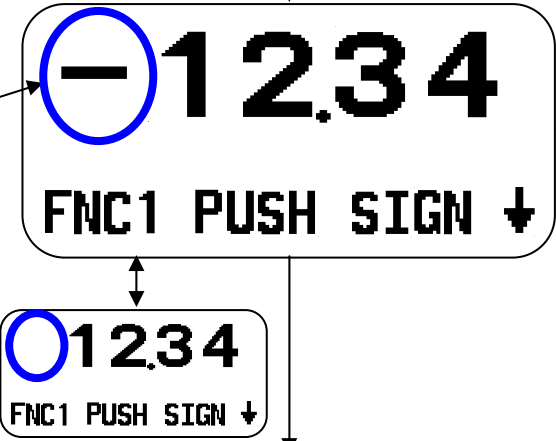
The parameters are shown in the below table.

| Items                  | Description  | Range                  |
|------------------------|--|------------------------|
| Sign of Push direction | The sign at the position of the direction of Push is set.<br>If it sets "-" and the stand moves to Push, the display of position is decrement.   | [space], -             |
| Acceleration           | The acceleration of the motor of the stand is set.<br>The acceleration is the slope or rate of increase in speed from the non-motion starting point to the set programmed speed.<br>If the parameter is set at a maximum of 100, the motor will accelerate quickly | 1 to 100 (step 1)      |
| Volume of buzzer       | The volume of the buzzer is adjusted.  | OFF, Low, Middle, High |

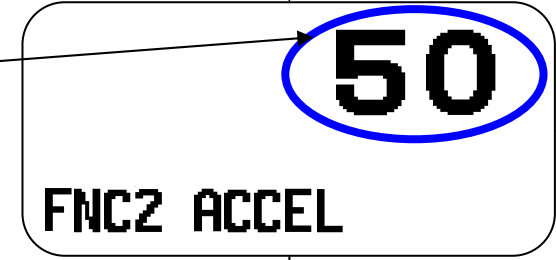
**Parameter**

If you want to cancel the setting, press **ZERO** button.

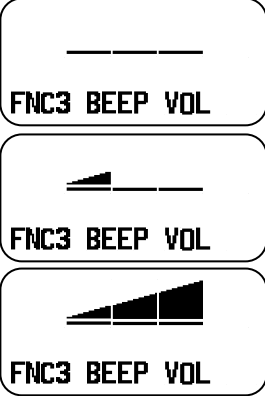
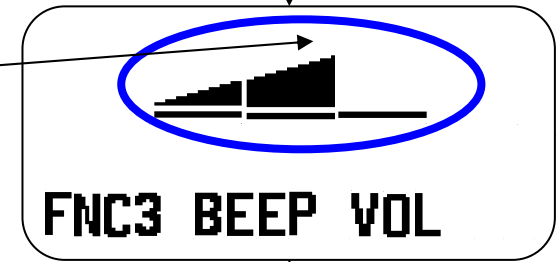
**Sign of Push direction**  
Space means '+'.  
Adjust with the **UP** or **DOWN** buttons. Pressing the button, the setting will be changed alternately.



**Acceleration**  
Adjust with the **UP** or **DOWN** buttons.



**Volume of buzzer**  
Adjust with the **UP** or **DOWN** buttons.

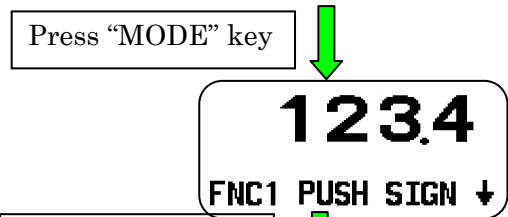


## 5.6 Changing Engineering Units

① Change distance and speed units in the function mode.

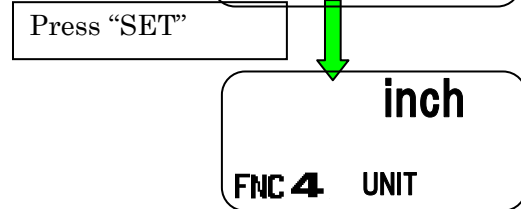
a) Function settings

Press "MODE" key to go to function settings



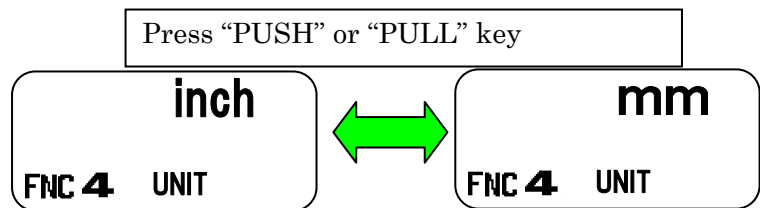
b) Changing the unit

Press "SET" key to go to FUNC4.



c) Change in the displayed unit

Pressing the "PUSH" or "PULL" keys changes the units from inch to mm



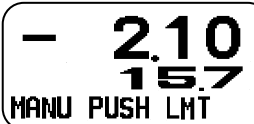
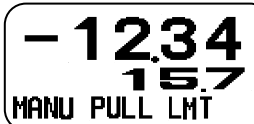
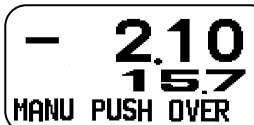
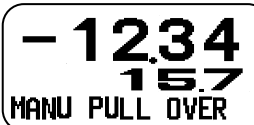




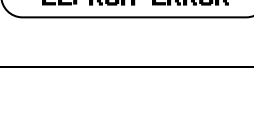

d) Registration of the unit

Press "SET" or "MODE" key to finish the setting

e) Note:

**The speed settings of JOG/MANU/SING/CONT/PROG go back to default when changing the units.**

## 6. Message of status and error

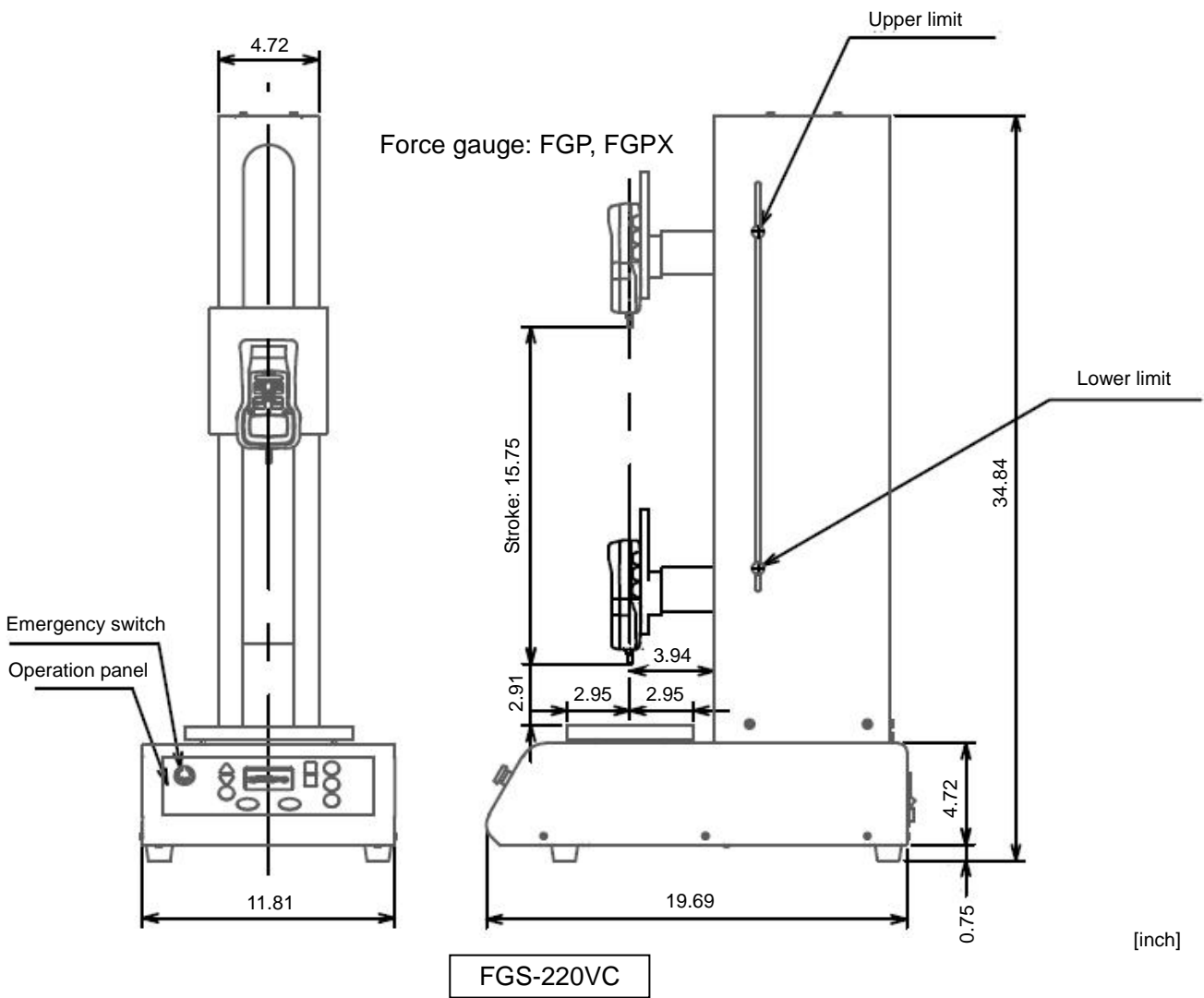
|   |   |  |
|---|---|--|
|    | <p>The lower limit was reached.<br/>“PUSH LMT” is blinking.</p>                                   | <p>If the status is abnormal, move the lower limit switch position.</p>  |
|    | <p>The upper limit was reached.<br/>“PULL LMT” is blinking.</p>                                   | <p>If the status is abnormal, move the upper limit switch position.</p>  |
|    | <p>The over load of the mounted force gauge occurred in push direction.</p>                       | <p>Confirm whether the force gauge used is correct.<br/>Check whether the measurement is abnormal.</p>   |
|    | <p>The over load of the mounted force gauge occurred in pull direction.</p>                       | <p>Confirm whether the force gauge used is correct.<br/>Check whether the measurement is abnormal.</p>   |
|    | <p>The emergency stop was pushed.</p>   | <p>Confirm that a problem is not found, then release the emergency stop.</p>   |
|  | <p>The motor or the driver of the motor was abnormal.</p>   | <p>Turn off and wait one minute, then turn on.<br/>Contact TECHNICAL SUPPORT if the alarm is not canceled.</p>   |
|  | <p>The communication error between the controller and the motor driver in the stand occurred.</p> | <p>Turn off and wait one minute, then turn on.<br/>Contact to our technical support if the error alarm is not canceled.</p>  |
|  | <p>The read error of the memory in the stand occurred.</p>  | <p>Turn off and wait one minute, then turn on.<br/>If the error is not canceled, initialize the parameter. Refer to the below procedure of the initialization.</p> |
|  | <p>The write error of the memory in the stand occurred.</p>                                       | <p>Turn off and wait one minute, then turn on.<br/>If the error is not canceled, initialize the parameter. Refer to the below procedure of the initialization.</p> |
|  | <p>The stand could not recognize the mounted force gauge.</p>                                     | <p>Check:<br/>The parameters setting of the force gauge, the sequence of power on and the cable.<br/>If no problem, ask to our technical support.</p>              |

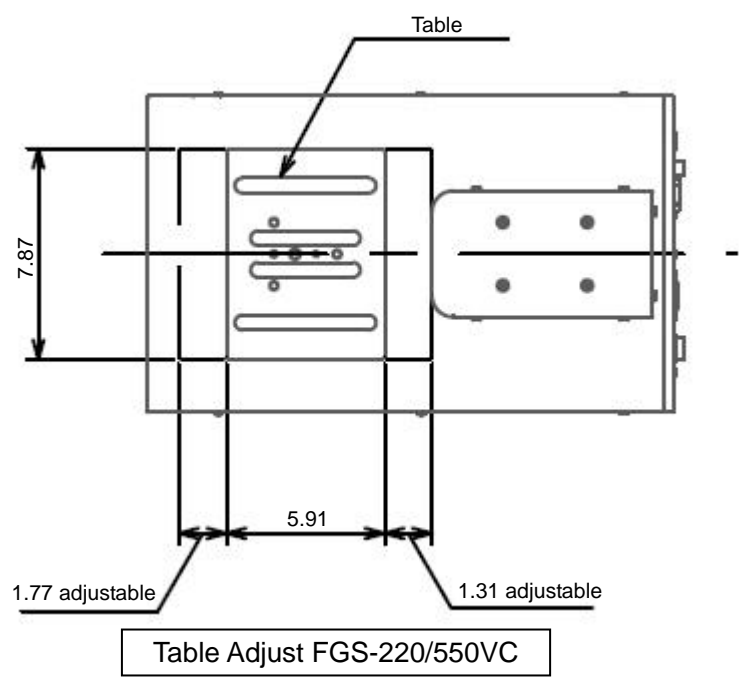
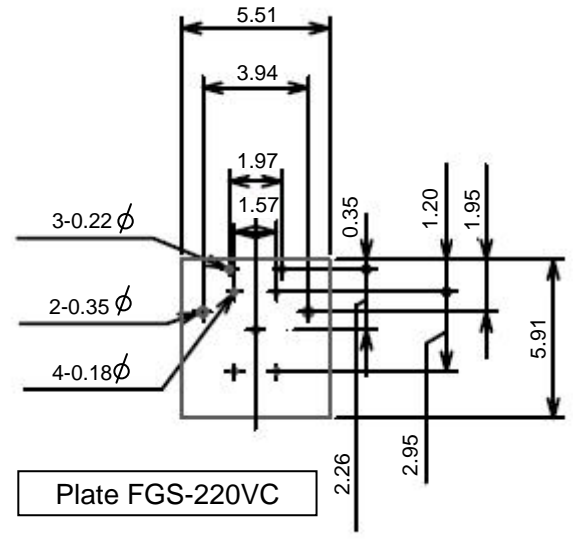
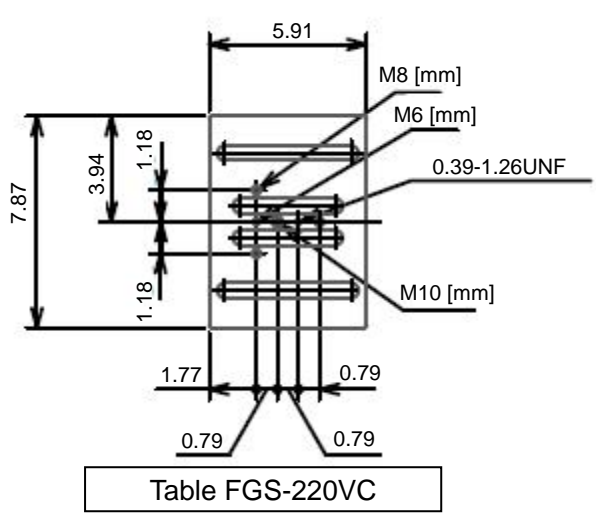
Procedure of the initialization of the parameters

1. Turn off, wait one minute.
2. Press **ZERO** and **SET** button both, turn on in keeping to press these buttons.

**FGS-220VC**  
**PARAMETER INIT**

**7. Dimensions**





[inch]



## 8. Specifications

| Model                 | FGS-220VC   |
|-----------------------|---|
| Capacity              | 100kg (1,000N, 220lb)   |
| Travel Speed          | 10-400mm/min (0.40-15.75"/min)  |
| Stroke                | 400mm (15.75")  |
| Display               | Dot-matrix LCD Four digit with sign   |
| Operating Mode        | MANU, JOG, SING, CONT, PROG   |
| Communication         | USB   |
| Input                 | Over load from force gauge (The stand will stop immediately, if the over load is detected.) |
| Measurement Table     | 150 x 200mm (5.91 x 7.87")  |
| Operating Temperature | 32-113 degrees Fahrenheit(0-45 degrees Centigrade)  |
| Power                 | 120VAC  |
| Weight                | 63kg (139lb)  |
| Dimensions            | 300 x 885 x 500mm (11.81 x 34.84 x 19.69")  |
| Accessories           | USB cable<br>Communication cable for force gauge(FGV series)                                |
| PC Software           | Free software is provided.  |
| Available Force Gauge | FGV-series Force gauge  |

## 9. Troubleshooting

The following are general checkpoints; please call your local Shimpo representative or contact Shimpo Instruments directly for further assistance.

|   |  |
|---|--|
| Even if the power supply is turned on, LCD doesn't display. | Confirm the voltage of the input supply.   |
| The force gauge/load cell mounting plate does not move.     | Check power connections and power source, ensure that test stand power is on.<br>Check whether the load hangs too much.<br>Check manual limit switches and adjust accordingly.<br>Confirm whether the emergency switch is ON.<br>Check the mounted force gauge is over load.<br>Check to see if the full travel range has already been achieved.<br>Check to be sure you are in the correct mode of operation. |
| The stand will not accept a program.                        | Move force gauge/load cell mounting plate to Home position.<br>Check to see if you are in the correct mode of operation (PROG).  |
| The stand is noisy during operating.                        | If there is no abnormal condition, the sound of the motor and gears may still be high due to rapid movement.   |

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## **NIDEC-SHIMPO AMERICA CORPORATION**

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1701 Glenlake Avenue Itasca, IL60143 USA  
Phone:(800)237-7079 FAX:(630)924-7639